

# Ziqi Pang

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## EDUCATION

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**University of Illinois Urbana-Champaign (UIUC)**

Doctor of Philosophy in Computer Science

*September 2021 - Current*

Advisor: Prof. Yu-Xiong Wang

**Peking University (PKU)**

Bachelor of Science in Computer Science, Cum Laude

*September 2016 - June 2020*

GPA: 3.74/4.00, Top 15%

**Carnegie Mellon University (CMU)**

Summer Research Assistant

*May 2019 - September 2019*

Advisor: Prof. Martial Hebert

## RESEARCH, WORKING, AND INTERNSHIP EXPERIENCE

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**University of Illinois Urbana-Champaign, Ph.D. Student**

*September 2021 - Current*

◦ Spatial-temporal reasoning in 3D perception. (1) Offboard HD-Map auto-labeling using NeRF ([MV-Map](#) - ICCV 2023); (2) streaming motion forecasting, which bridges the gap between forecasting datasets and the real world streaming traffic ([Streaming Forecasting](#) - IROS 2023); (3) end-to-end vision-centric 3D MOT, significantly decreases the ID-Switches by end-to-end tracking and motion prediction ([PF-Track](#) - CVPR 2023).

◦ Enhancing visual encoders from language models. Frozen transformers in language models are effective visual encoder layers ([LM4VE](#) - ICLR 2024 Spotlight).

◦ Video object segmentation in state-changing scenarios. Proposing better long-term memory mechanisms for video object segmentation and its hardest scenarios of state-changing (RMem - CVPR 2024).

**Toyota Research Institute, Research Intern**

*May 2022 - December 2022*

◦ 3D tracking and motion forecasting from multiple cameras. End-to-end & BEV MOT and motion prediction, decreases tracking errors (ID-Switches) by more than 90% on nuScenes compared to previous state-of-the-arts ([PF-Track](#) - CVPR 2023).

**TuSimple, AI Residency for Perception in Self-driving**

*June 2020 - August 2021*

◦ LiDAR-based 3D perception for autonomous driving. Public projects: (1) the first transformer-based outdoor 3D detection method, features the sparsity of point clouds and perform well on small objects ([SST](#) - CVPR 2022); (2) a widely used and robust 3D multi-object tracking framework ([Simple-Track](#) - ECCVW 2022 and patent); (3) onboard redundancy system and offboard object auto-labeling from single-object tracking ([LiDAR-SOT](#) - IROS 2021).

## PEER-REVIEWED PUBLICATIONS

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**Restricted Memory Banks Improve Video Object Segmentation: A Revisit** [RMem]

*Junbao Zhou\*, [Ziqi Pang\\*](#), Yu-Xiong Wang*

**CVPR 2024**

**Frozen Transformers in Language Models Are Effective Visual Encoder Layers** [[LM4VE](#)]

*Ziqi Pang, Ziyang Xie\*, Yunze Man\*, Yu-Xiong Wang*

**ICLR 2024 (Spotlight)**

**MV-Map: Offboard HD-Map Generation with Multi-view Consistency** [[MV-Map](#)]

*Ziyang Xie\*, [Ziqi Pang\\*](#), Yu-Xiong Wang*

**ICCV 2023**

**Streaming Motion Forecasting for Autonomous Driving** [[Streaming Forecasting](#)]

*Ziqi Pang, Deva Ramanan, Mengtian Li, Yu-Xiong Wang*

**IROS 2023**

**Standing Between Past and Future: Spatio-Temporal Modeling for Multi-Camera 3D Multi-Object Tracking** [[PF-Track](#)]

*Ziqi Pang, Jie Li, Pavel Tokmakov, Dian Chen, Sergey Zagoruyko, Yu-Xiong Wang*

**CVPR 2023**

**Embracing Single Stride 3D Object Detector with Sparse Transformer** [[SST](#)]

*Lue Fan, Ziqi Pang, Tianyuan Zhang, Yu-Xiong Wang, Hang Zhao, Feng Wang, Naiyan Wang, Zhaoxiang Zhang*

**CVPR 2022**

**SimpleTrack: Understanding and Rethinking 3D Multi-object Tracking** [[SimpleTrack](#)]

*Ziqi Pang, Zhichao Li, Naiyan Wang*

**ECCV Workshop 2022, Patented 2023**

**Model-free Vehicle Tracking and State Estimation in Point Cloud Sequences** [[LiDAR-SOT](#)]

*Ziqi Pang, Zhichao Li, Naiyan Wang*

**IROS 2021**

## PREPRINTS

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**Unlocking the Full Potential of Small Data with Diverse Supervision** [[SmallData](#)]

*Ziqi Pang\**, *Zhiyuan Hu\**, *Pavel Tokmakov*, *Yu-Xiong Wang*, *Martial Hebert*

**Arxiv Preprint 2021**

**Immortal Tracker: Tracklet Never Dies** [[ImmortalTracker](#)]

*Qitai Wang*, *Yuntao Chen*, *Ziqi Pang*, *Naiyan Wang*, *Zhaoxiang Zhang*

**Arxiv Preprint 2021**

## PATENTS

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**Multiple target tracking method and apparatus, calculating device and storage medium**

*Ziqi Pang, Zhichao Li, Naiyan Wang*

US Patent App. 17/816,239, 2023

## SERVICES

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**Teaching Assistants for CS 446 (Machine Learning) and CS 445 (Computational Photography)** at University of Illinois Urbana-Champaign (UIUC), and **ICS (Introduction to Computer System)** at Peking University (PKU).

**Reviewer** for CVPR, ICCV, ECCV, NeurIPS, ICLR, ICML, RA-L, ICRA, IROS.

## AWARDS AND SCHOLARSHIPS

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**Outstanding Graduate** at Peking University

*June 2020*

**Peking University Scholarship** at Peking University (Top 5%)

*September 2018*

**Kwung-hua Scholarship** at Peking University (Top 5%)

*September 2017*